

Software implementations of ECC: security and efficiency

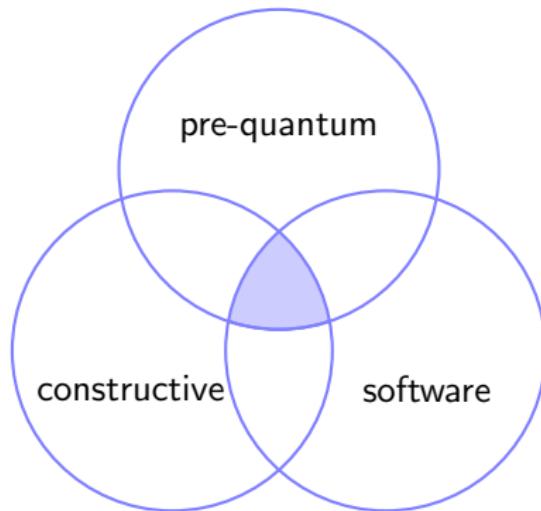
Tung Chou

Osaka University

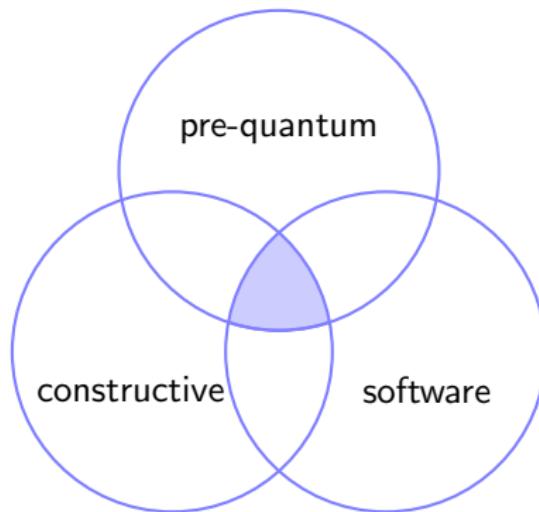
17 November 2018

Summer School of the ECC workshop

Scope



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- : small exercises, homework

Diffie-Hellman key-exchange (agreement)

Parties agreed on: **group** $G = \langle g \rangle$
(e.g., $G \subset \mathbb{Z}_p^*$)

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$$g^a$$



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$$g^b$$



$$s = (g^b)^a$$

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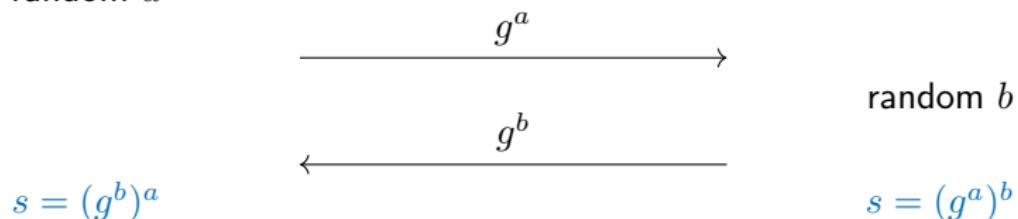
$$s = (g^a)^b$$

- “Assumed” to be “hard”
 - recovering c from g^c
 - recovering g^{ab} given g, g^a, g^b

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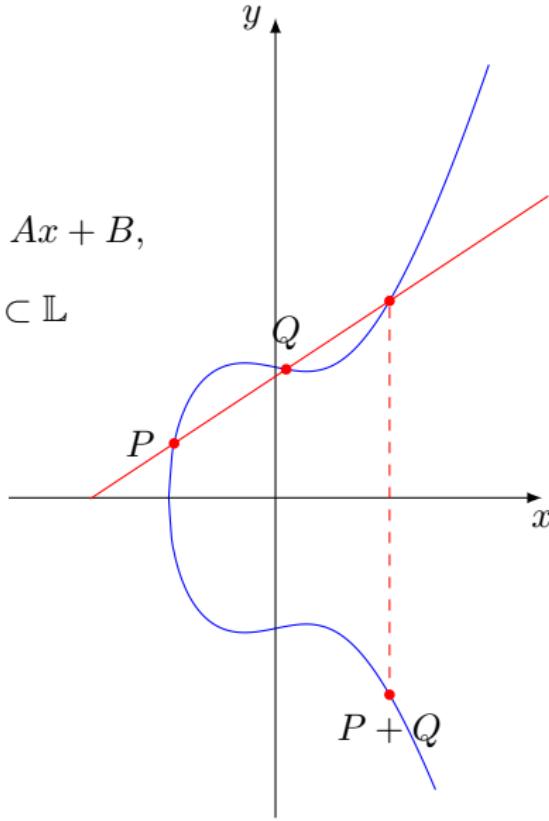


- “Assumed” to be “hard”
 - recovering c from g^c
 - recovering g^{ab} given g, g^a, g^b
- Security depends on G

Elliptic curves

$$E : y^2 = x^3 + Ax + B,$$

$$A, B \in \mathbb{K} \subset \mathbb{L}$$



$$E(\mathbb{L}) = \{\infty\} \cup \{(x, y) \in \mathbb{L}^2 \mid y^2 = x^3 + Ax + B\}$$

Elliptic-curve Diffie-Hellman

Parties agreed on: **curve** E , $\langle B \rangle \subseteq E(\mathbb{K})$

random a

$$\xrightarrow{aB}$$

random b

$$\xleftarrow{bB}$$

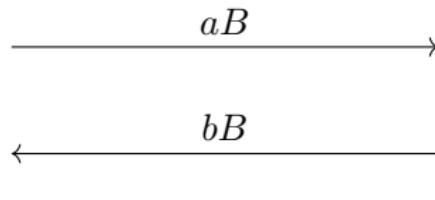
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Elliptic-curve Diffie-Hellman

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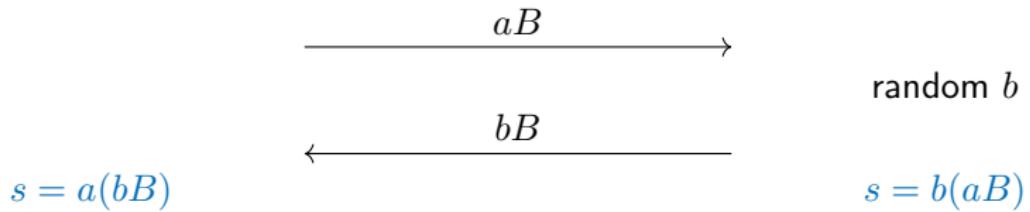
random a



Elliptic-curve Diffie-Hellman

Parties agreed on: **curve** E , $\langle B \rangle \subseteq E(\mathbb{K})$

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“Assumed” to be “hard”

- recovering k from kP
- recovering abP given P, aP, bP

Scalar multiplications

$$k \cdot P$$

Scalar multiplications

$$k \cdot P$$



scalar

(secret? public?)

base point

(fixed? variable?)

safecurves.cr.yp.to/

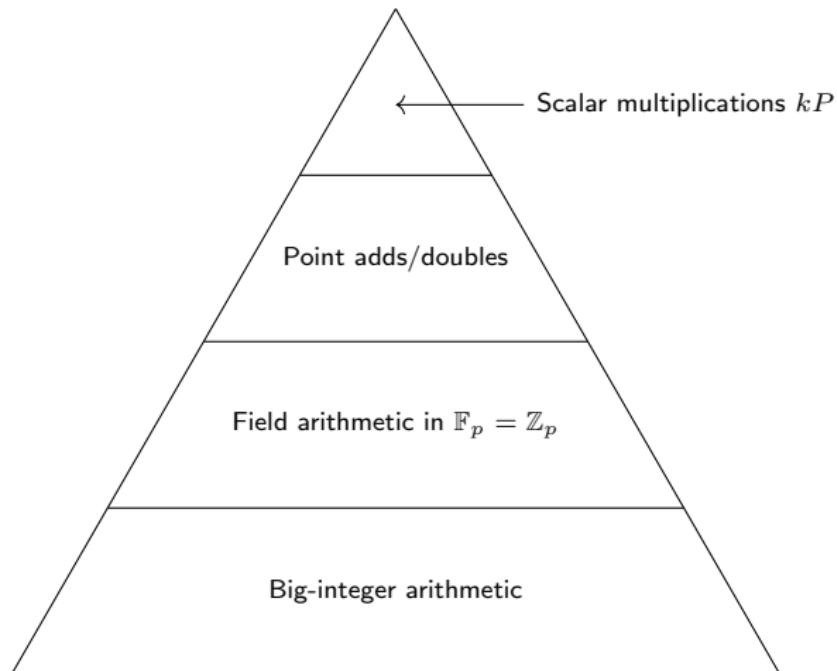
Curve	Safe?	Details
Anomalous	False	$y^2 = x^3 + 1534789805537158059089057672131431882320753196305637503096292x + 7444386449934505970367865204569124728350661870959593404279615$ modulo p = 17676318486848893030961583018778670610489016512983351739677143 Created as an illustration of additive transfer and small discriminant.
M-221	True ✓	$y^2 = x^3 + 117050x^2 + x$ modulo p = $2^{221} - 3$ 2013 Aranha-Barreto-Pereira-Ricardini (formerly named Curve2213)
E-222	True ✓	$x^2 + y^2 = 1 + 160102x^2y^2$ modulo p = $2^{222} - 17$ 2013 Aranha-Barreto-Pereira-Ricardini
NIST P-224	False	$y^2 = x^3 - 3x + 1895828628556660800040866854493926415504680968679321075787234672564$ modulo p = $2^{224} - 2^{96} + 1$ 2000 NIST ; also in SEC 2
Curve1174	True ✓	$x^2 + y^2 = 1 - 1174x^2y^2$ modulo p = $2^{251} - 9$ 2013 Bernstein-Hamburg-Krasnova-Lange
Curve25519	True ✓	$y^2 = x^3 + 486662x^2 + x$ modulo p = $2^{255} - 19$ 2006 Bernstein
BN(2,254)	False	$y^2 = x^3 + 0x + 2$ modulo p = 16798108731015832284940804142231733909889187121439069848933715426072753864723 2011 Pereira-Simplicio-Naehrig-Barreto pairing-friendly curve. Included as an illustration of multiplicative transfer and small discriminant.
brainpoolP256t1	False	$y^2 = x^3 - 3x + 46214326585032579593829631435610129746736367449296220983687490401182983727876$ modulo p = 76884956397045344220809746629001649093037950200943055203735601445031516197751 2005 Brainpool
ANSSI FRP256v1	False	$y^2 = x^3 - 3x + 107744541122042688792155207242782455150382764043089114141096634497567301547839$ modulo p = 109454571331697278617670725030735128145969349647868738157201323556196022393859 2011 ANSSI

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- Different curves forms
- Large field sizes: typically $> 2^{200}$

ECC implementation pyramid



Explicit-Formulas Database

Bibliography

Genus-1 curves over large-characteristic fields

Doubling-oriented Doche-Icart-Kohel curves: $y^2 = x^3 + a*x^2 + 16*a*x$

Tripling-oriented Doche-Icart-Kohel curves: $y^2 = x^3 + 3*a*(x+1)^2$

Edwards curves: $x^2 + y^2 = c^2 * (1 + d*x^2*y^2)$

Hessian curves: $x^3 + y^3 + 1 = 3*d*x*y$

Jacobi intersections: $s^2 + c^2 = 1, a*s^2 + d^2 = 1$

Jacobi quartics: $y^2 = x^4 + 2*a*x^2 + 1$

Montgomery curves: $b*y^2 = x^3 + a*x^2 + x$

Short Weierstrass curves: $y^2 = x^3 + a*x + b$

Twisted Edwards curves: $a*x^2 + y^2 = 1 + d*x^2*y^2$

Twisted Hessian curves: $a*x^3 + y^3 + 1 = d*x*y$

Ordinary genus-1 curves over binary fields

Binary Edwards curves: $d1*(x+y) + d2*(x^2 + y^2) = (x + x^2)*(y + y^2)$

Hessian curves: $x^3 + y^3 + 1 = 3*d*x*y$

Short Weierstrass curves: $y^2 + x*y = x^3 + a2*x^2 + a6$

Explicit formulas for addition

The "mmadd-2008-hwcd-4" addition formulas [[database entry](#); [Sage verification script](#); [Sage output](#); [three-operand code](#)]:

- Assumptions: $Z_1=1$ and $Z_2=1$.
- Cost: $6M + 8\text{add} + 2^*2$.
- Cost: $6M + 6\text{add} + 1^*2$ dependent upon the first point.
- Source: 2008 Hisil-Wong-Carter-Dawson, <http://eprint.iacr.org/2008/522>, Section 3.2, plus assumption $Z_1=1$.
- Explicit formulas:

```
A = (Y1-X1)*(Y2+X2)
B = (Y1+X1)*(Y2-X2)
C = 2*T2
D = 2*T1
E = D+C
F = B-A
G = B+A
H = D-C
X3 = E+F
Y3 = G*H
T3 = E*H
Z3 = F*G
```

Naive scalar multiplication

- Input: scalar k , point P
- Output: kP

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- Way too slow... (recall the group order)

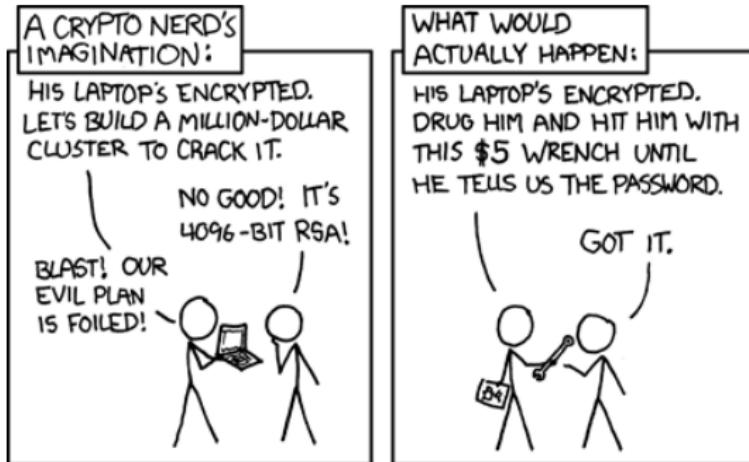
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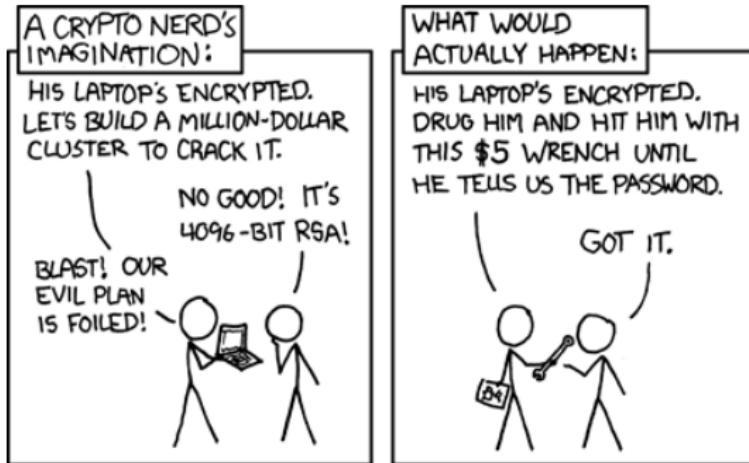
- Way too slow... (recall the group order)
- Timing depends on k (secret)!

Theory versus reality



(picture from xkcd.com/538/ [CC BY-NC 2.5])

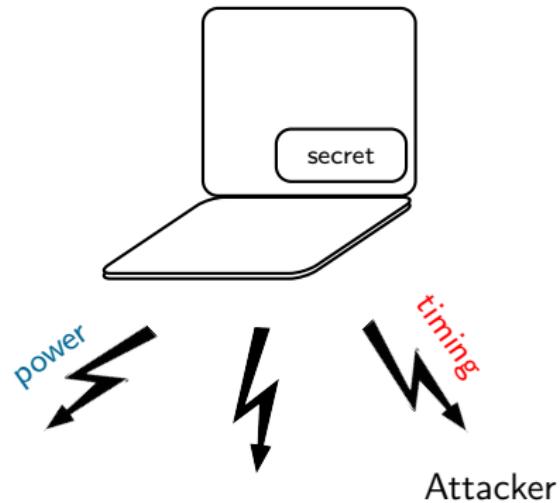
Theory versus reality



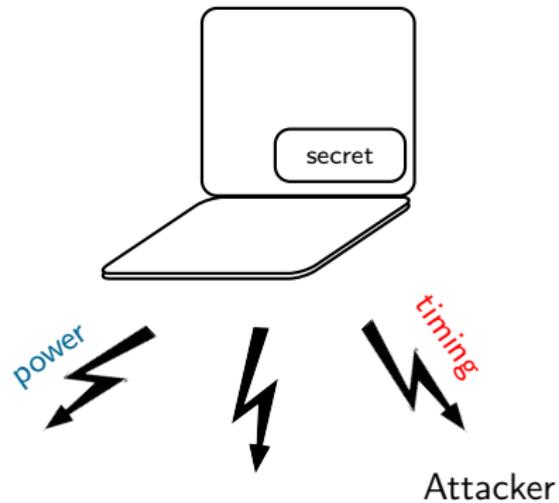
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- How about the attack scenarios between the 2 cases?

Side channels

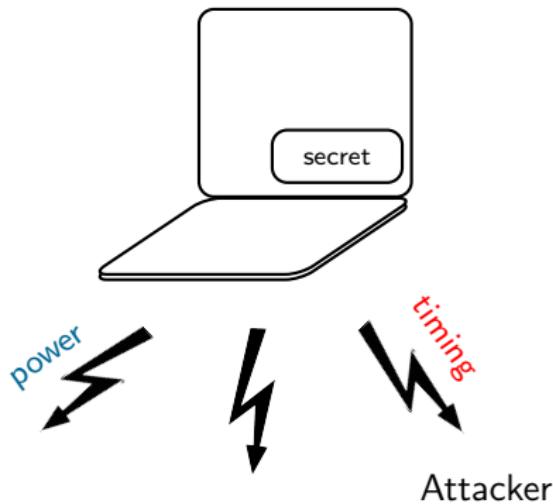


Side channels



- Side channel information might be correlated to the secret(s)

Side channels



- Side channel information might be correlated to the secret(s)
- We need **constant-time** implementations
 - timing should be independent of the secret(s)

Scalar multiplications with double-and-add

- Input: $k = (k_{\ell-1} k_{\ell-2} \dots k_0)_2$, point P
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    Q = 2Q
    if k[i] == 1
        Q += P
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- Similarly, we can do “square-and-multiply”
- From LSB to MSB?

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    if k[i] == 1 ← timing difference!
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    R0 = 2Q
    R1 = Q + P
    if k[i] == 1
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Q = 0
For i from l-1 downto 0 do
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    if k[i] == 1 ← branch prediction
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(...and also the problem with instruction cache)

Branch prediction

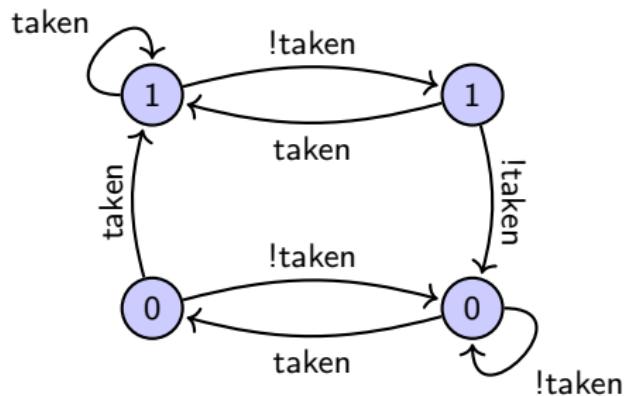
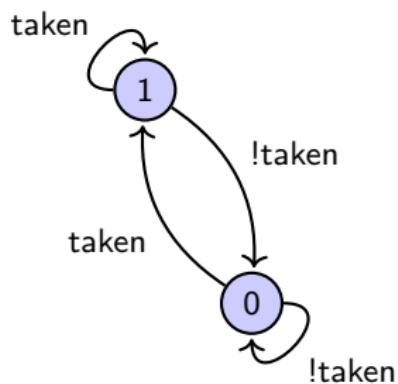
1 : predict taken

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Branch prediction

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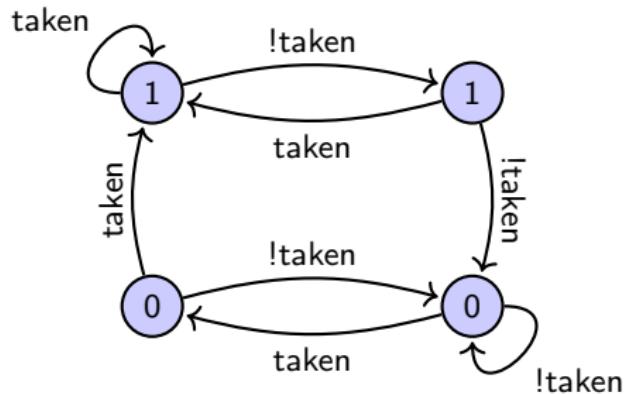
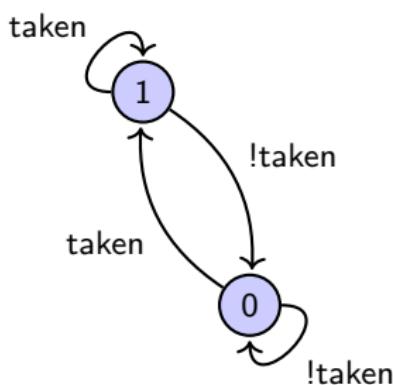
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Branch prediction

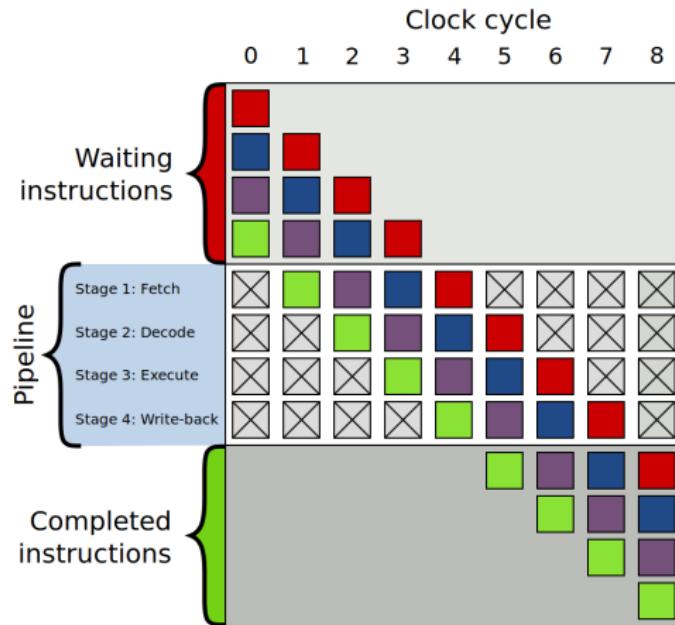
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-
- Good for loop structures. Why?

Branch prediction (cont.)



(picture from en.wikipedia.org/wiki/Branch_predictor [CC BY-SA 3.0])

Scalar multiplications with double-and-add

- Input: $k = (k_{\ell-1}k_{\ell-2}\dots k_0)_2$, point P
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$Q = 0$

For i from $\ell-1$ downto 0 do

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$Q = \text{SEL}(R, Q, k[i])$ ← constant-time

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$\text{SEL}(R, Q, b)$:

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mask_R = -b
mask_Q = ~mask_R
```

```
return (mask_R & R) | (mask_Q & Q)
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$\text{return } (\text{mask_R} \& R) \mid (\text{mask_Q} \& Q)$

- Still many dummy operations

Scalar multiplications with table lookups (fixed window)

- Group w bits. Keep a table of $0P, \dots, (2^w - 1)P$

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```
For i from 0 to 15 do
    T[i] = iP

Q = 0
For i in [252, 248, ..., 0] do

    j = (k[i+3] k[i+2] k[i+1] k[i])_2

    Q = 2Q
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    Q += T[j]
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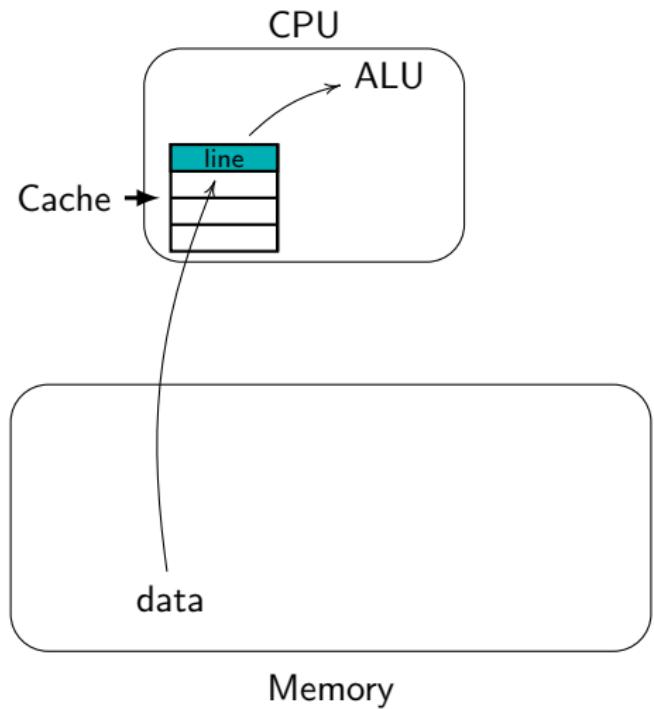
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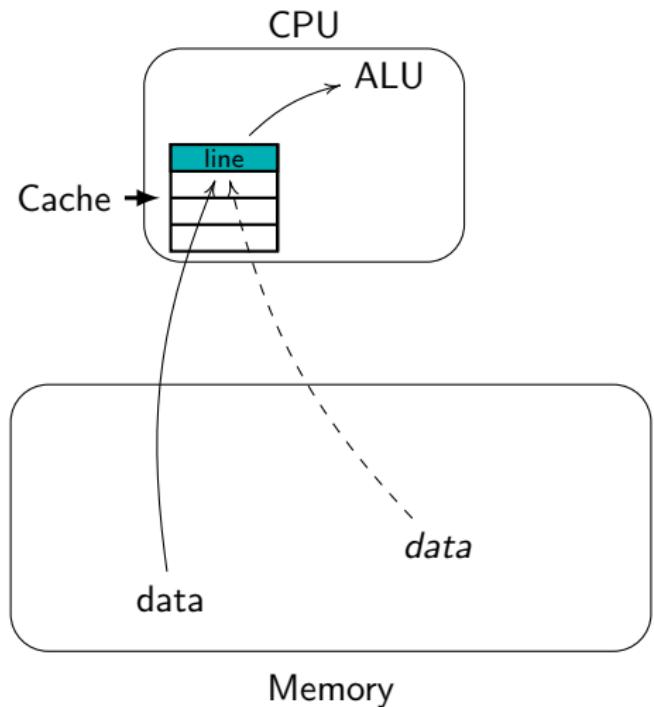
```
    Q += T[j] ← non-constant-time!
```

- $\approx \ell/w$ additions

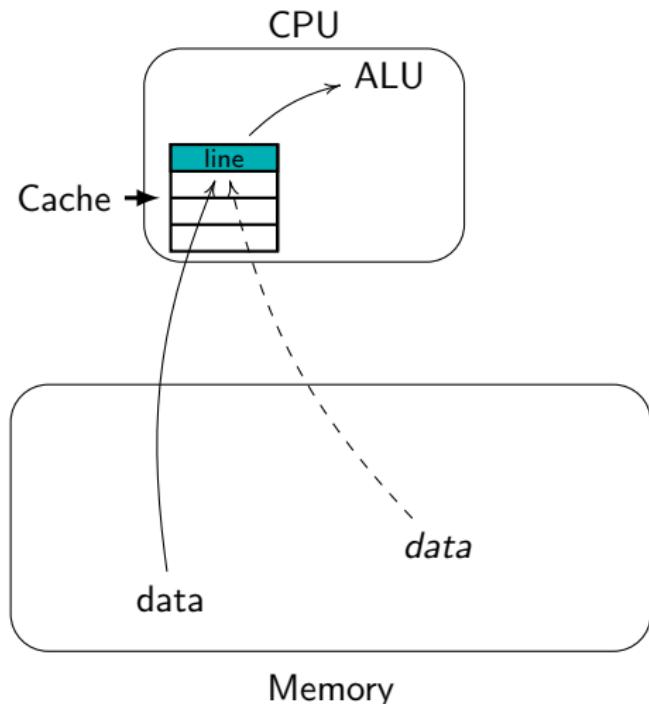
Caches



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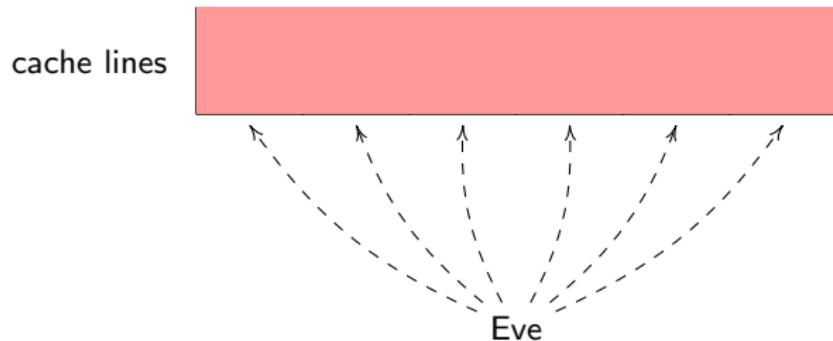
- Real architectures are more complex (hierarchy, associativity, etc)
- Instruction caches

Cache-timing attacks

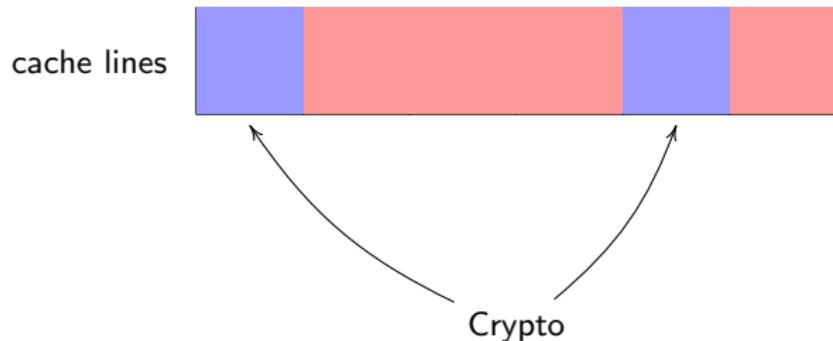


Eve

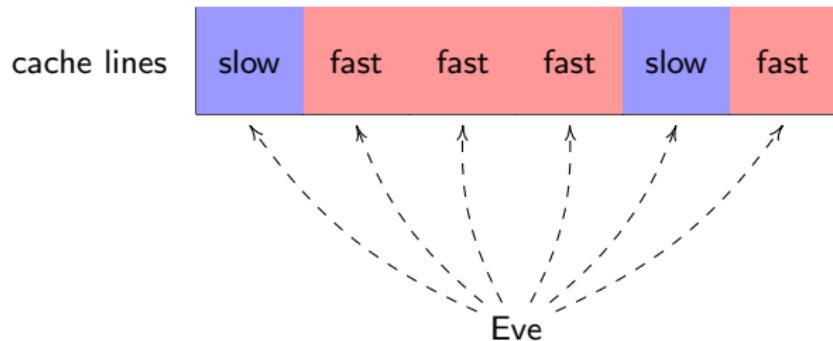
Cache-timing attacks



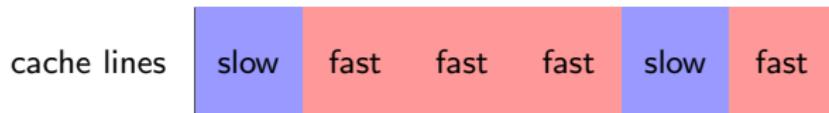
Cache-timing attacks



Cache-timing attacks



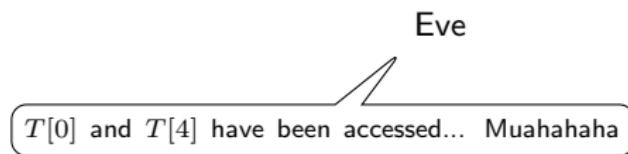
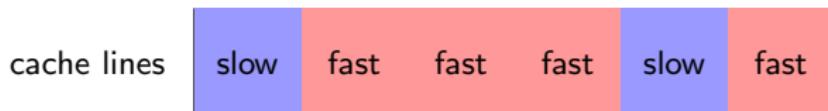
Cache-timing attacks



Eve

T[0] and T[4] have been accessed... Muahahaha

Cache-timing attacks



- Similar for instruction cache
- To avoid timing attacks, you should avoid
 - secret-dependent conditions
 - secret-dependent memory indices

Constant-time table lookups

- Consider $w = 3$

```
// compute mask_j from i s.t.  
// mask_j = 0xFF..F if j == i  
// mask_j = 0x00..0 if j != i  
  
v = mask_0 & T[0];  
v |= mask_1 & T[1];  
v |= mask_2 & T[2];  
v |= mask_3 & T[3];  
v |= mask_4 & T[4];  
v |= mask_5 & T[5];  
v |= mask_6 & T[6];  
v |= mask_7 & T[7];  
  
// now v = T[i]
```

Constant-time table lookups

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v |= mask_5 & T[5];  
v |= mask_6 & T[6];  
v |= mask_7 & T[7];  
  
// now v = T[i]
```

- There is a limit on w

Signed window

- Each window is consider to be in $[-2^{w-1}, 2^{w-1} - 1]$
- $\bar{1}$ denotes -1

$$(\underline{01} \ \underline{10} \ \underline{11} \ \underline{01} \ \underline{11})_2$$

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$$(\textcolor{blue}{10} \ \textcolor{blue}{0\bar{1}} \ 0\bar{1} \ 10 \ 0\bar{1})_2$$

- Rewriting is cheap

On-demand negation

```
// compute mask_j from i s.t.  
// mask_j = 0xFF..F if |j| == i  
// mask_j = 0x00..0 if |j| != i  
  
v = mask_0 & T[0];  
v |= mask_1 & T[1];  
v |= mask_2 & T[2];  
v |= mask_3 & T[3];  
v |= mask_4 & T[4];  
  
v = SEL(-v, v, sign(j));  
  
// now v = T[i]
```

- More memory-efficient
- More time-efficient (negation is cheap)

Fixed-base scalar multiplication

- Precomputation is free...
 - can use large window sizes (still many squarings).
 - can just precompute all $2^i P$ and do additions (no doublings).

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- Suppose each table entry takes 64 bytes, $\ell = 256$ and $w = 4$.
Memory requirement?

Variable-time instructions

						latency	
MULX	r32,r32,r32	3	3	p1 2p056	4	1	
MULX	r32,r32,m32	3	4	p1 2p056 p23		1	
MULX	r64,r64,r64	2	2	p1 p6	4	1	
MULX	r64,r64,m64	2	3	p1 p6 p23		1	
DIV	r8	9	9	p0 p1 p5 p6	22-25	9	
DIV	r16	11	11	p0 p1 p5 p6	23-26	9	
DIV	r32	10	10	p0 p1 p5 p6	22-29	9-11	
DIV	r64	36	36	p0 p1 p5 p6	32-96	21-74	
IDIV	r8	9	9	p0 p1 p5 p6	23-26	8	
IDIV	r16	10	10	p0 p1 p5 p6	23-26	8	
IDIV	r32	9	9	p0 p1 p5 p6	22-29	8-11	
IDIV	r64	59	59	p0 p1 p5 p6	39-103	24-81	

http://www.agner.org/optimize/instruction_tables.pdf

EdDSA signature scheme

B : based point, $\ell = |B|$, \mathcal{H} : hash function with $2b$ -bit outputs

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Key generation:

k : b -bit secret key

$$a \leftarrow \mathcal{H}(k)$$

$$A \leftarrow aB : \text{public key}$$

Signing:

$$r \leftarrow \mathcal{H}(a, M)$$

$$R \leftarrow rB$$

$$s \leftarrow (r + \mathcal{H}(R, A, M)a) \mod \ell$$

(R, s) : signature of M

Verification:

$$sB = R + \mathcal{H}(R, A, M)A$$

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- Convince yourself that the scheme works.

Sliding window

- Keep mP with odd $m \in [0, 2^w - 1]$
- Shift the window if necessary

$(\underline{01} \ \underline{10} \ \underline{11} \ \underline{01} \ \underline{11})_2$

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$$\begin{array}{c} (\underline{01} \ \underline{10} \ \underline{11} \ \underline{01} \ \underline{11})_2 \\ \downarrow \\ (01 \ 10 \ 11 \ 01 \ \textcolor{blue}{03})_2 \end{array}$$

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- $4 \Rightarrow 3$ additions
- Can use signed sliding window

Double-scalar multiplications

- Input: public a, b , point P, Q
- Output: $aP + bQ$

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```
R = 0
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```

- Sliding window can be applied (even different window sizes)
- Multi-scalar multiplication

Montgomery curves

1987 Montgomery:

- Curve

$$by^2 = x^3 + ax^2 + x$$

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$$2(x_2, y_2) = (x_4, y_4) \Rightarrow x_4 = \frac{(x_2^2 - 1)^2}{4x_2(x_2^2 + ax_2 + 1)}$$

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$$\Rightarrow x_5 = \frac{(x_2x_3 - 1)^2}{x_1(x_2 - x_3)^2}$$

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- We can compute the x coordinate of kP !

- Represent (x, y) as

$$(X : Z), \quad x = X/Z$$

Montgomery ladder

Goal: compute $nP, n = (n_{\ell-1}n_{\ell-2}\cdots n_0)_2$

- Start from $(Q_\ell, R_\ell) = (0, P)$
- Maintain (Q_i, R_i) s.t. $R_i = Q_i + P$,

$$Q_i = \sum_{j=j}^{\ell} n_j 2^{j-i} P \quad (i \text{ decreasing})$$

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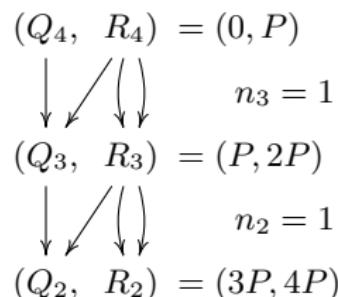
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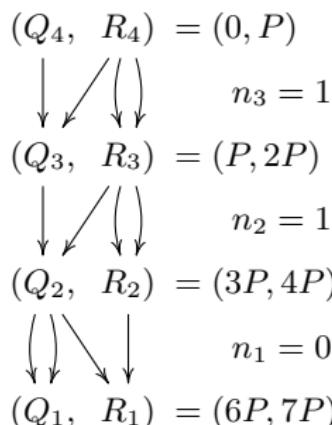
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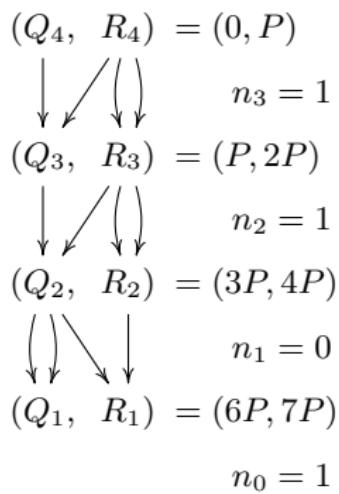
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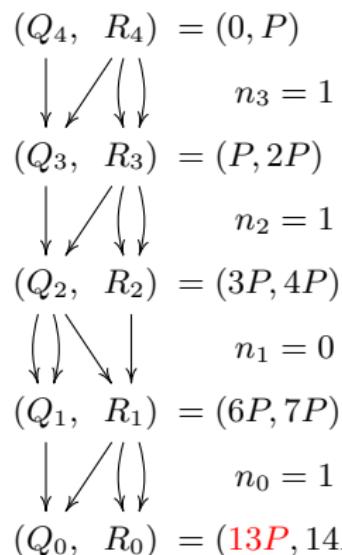
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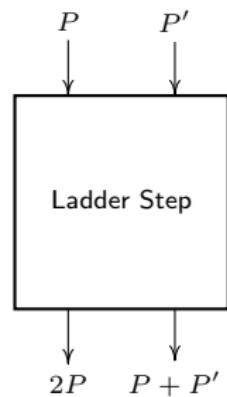
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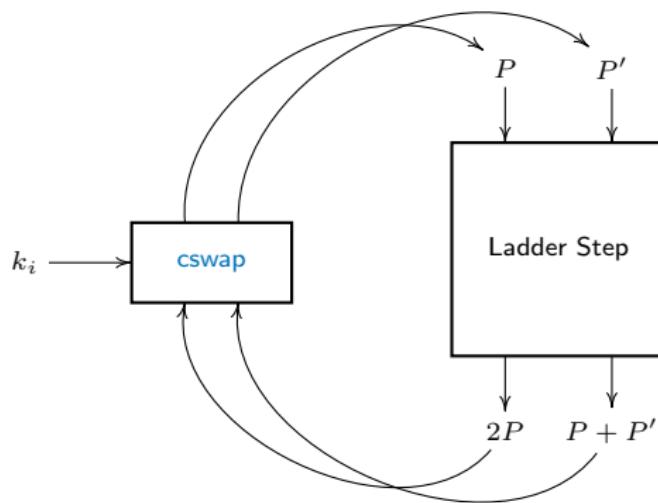
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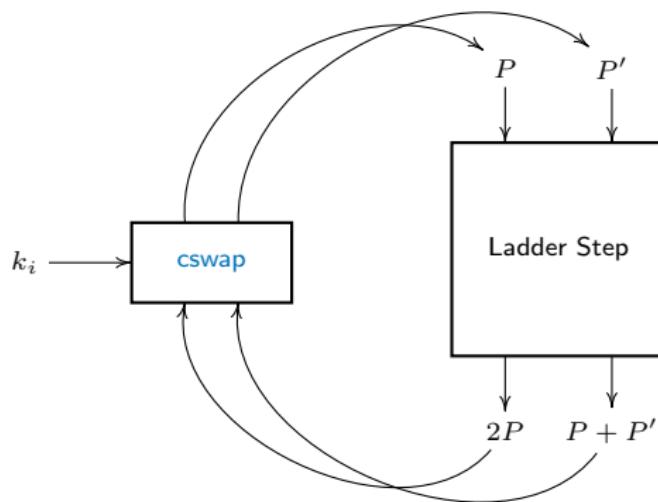
Implementing the Montgomery ladder



Implementing the Montgomery ladder



Implementing the Montgomery ladder



- How to implement **cswap**?
 - hint: 4 bit operations to conditionally swap 2 bits

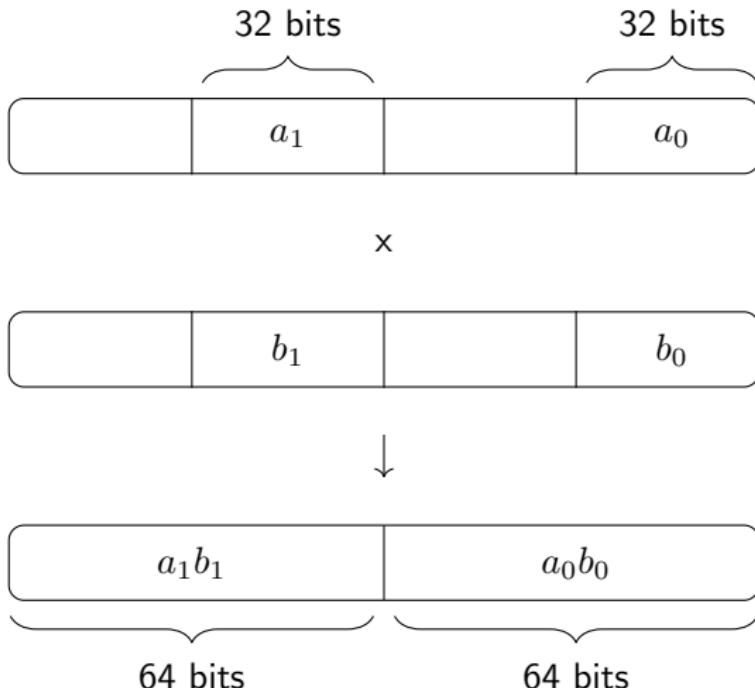
Vector units

- Advanced Vector Extensions (AVX)

511	256	255	128	127	0
ZMM0	YMM0	XMM0			
ZMM1	YMM1	XMM1			
ZMM2	YMM2	XMM2			
ZMM3	YMM3	XMM3			
ZMM4	YMM4	XMM4			
ZMM5	YMM5	XMM5			
ZMM6	YMM6	XMM6			
ZMM7	YMM7	XMM7			
ZMM8	YMM8	XMM8			
ZMM9	YMM9	XMM9			
ZMM10	YMM10	XMM10			
ZMM11	YMM11	XMM11			
ZMM12	YMM12	XMM12			
ZMM13	YMM13	XMM13			
ZMM14	YMM14	XMM14			
ZMM15	YMM15	XMM15			

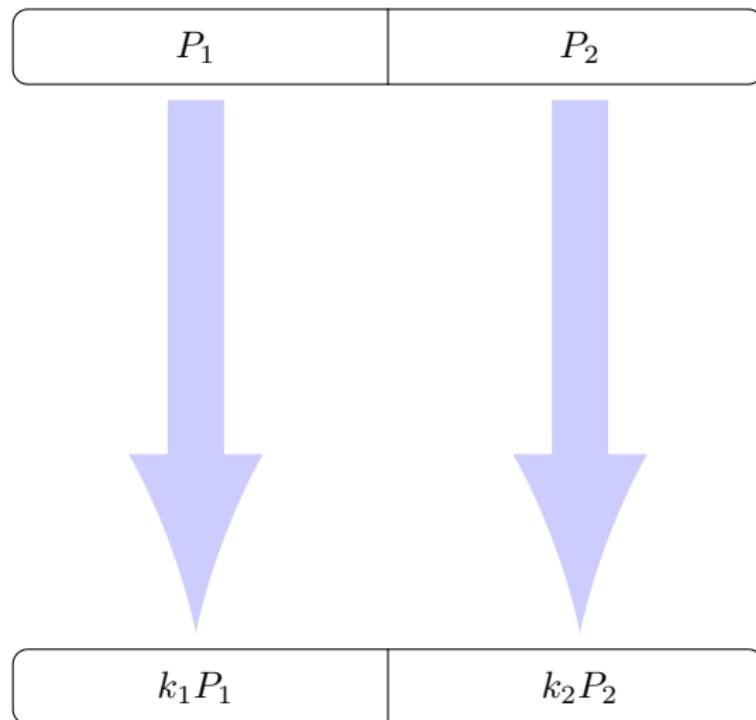
- Enables vector instructions

2-way vectorization

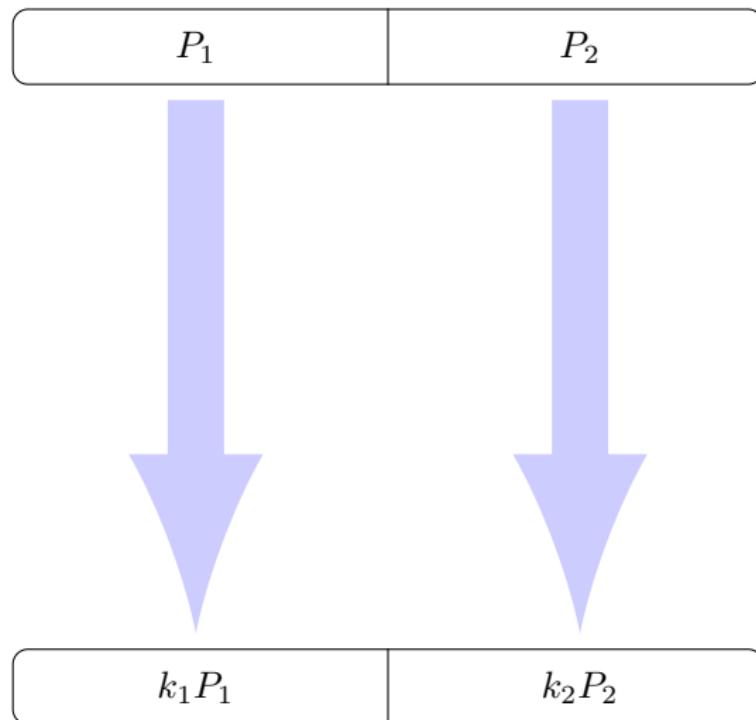


- Useful for accelerating cryptographic computation

Exploiting parallelism: naive way



Exploiting parallelism: naive way



- Might be good for busy servers. Other applications?

Exploiting parallelism: key generation

$$P = s_0B + s_116B + s_216^2B + \cdots + s_{63}16^{63}B$$

Exploiting parallelism: key generation

$$P = s_0B + s_116B + s_216^2B + \cdots + s_{63}16^{63}B$$



$$P_0 = s_0B + s_216^2B + \cdots + s_{62}16^{62}B$$

$$P_1 = s_1B + s_316^2B + \cdots + s_{63}16^{62}B$$

$$P = 16P_1 + P_0$$

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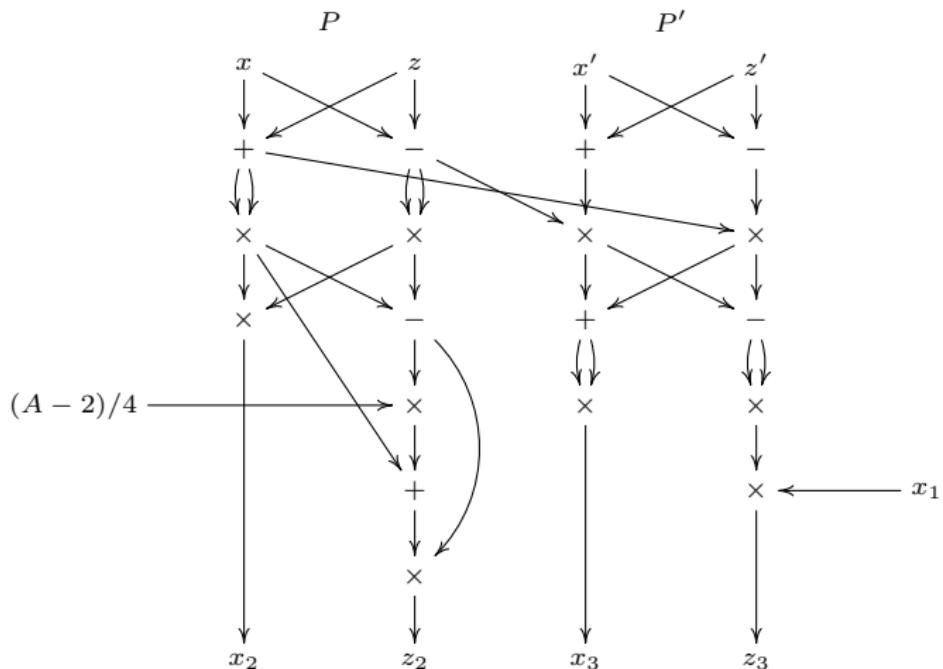
$$P_0 = s_0B + \boxed{s_216^2B} + \cdots + \boxed{s_{62}16^{62}B}$$

$$P_1 = s_1B + \boxed{s_316^2B} + \cdots + \boxed{s_{63}16^{62}B}$$

$$P = 16P_1 + P_0$$

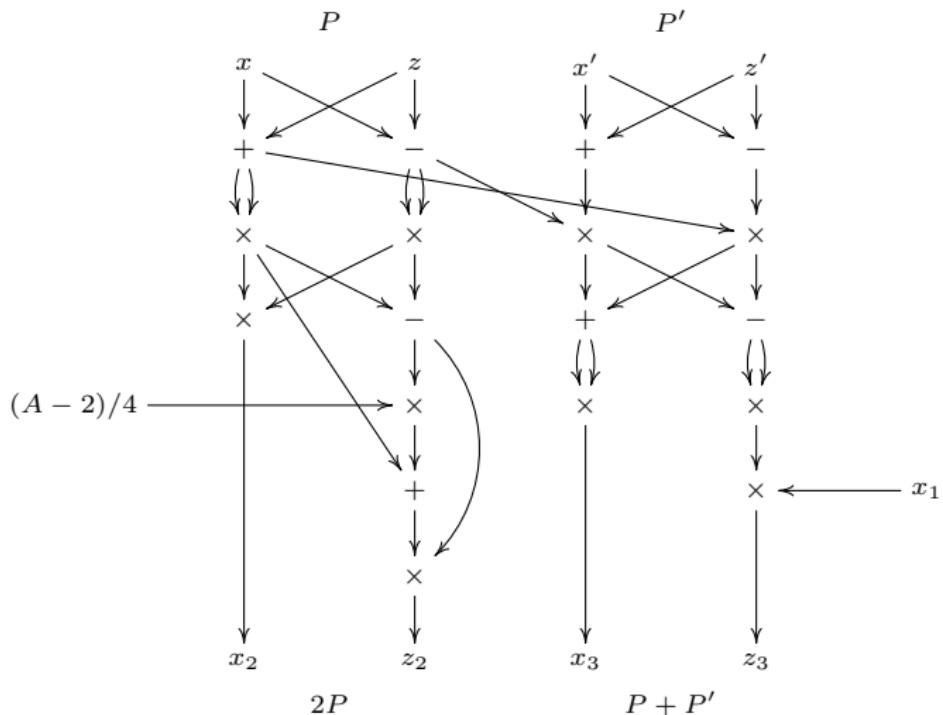
- Extra benefit of reducing table size
- Tradeoffs between time and space

Exploiting parallelism: ladder step



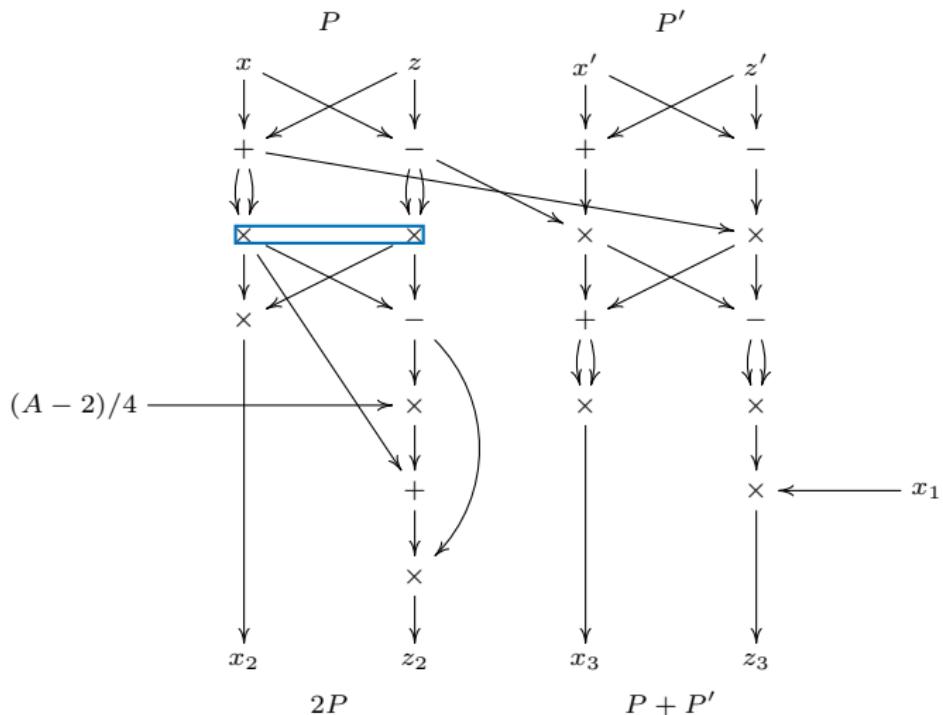
www.hyperelliptic.org/EFD/g1p/auto-montgom-xz.html#ladder-mladd-1987-m

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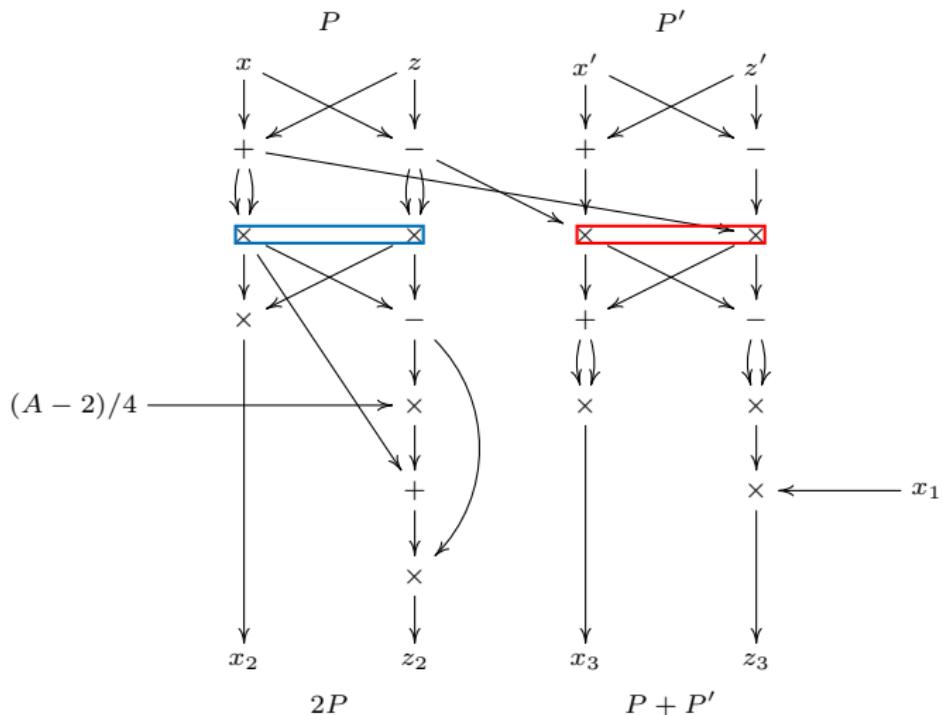
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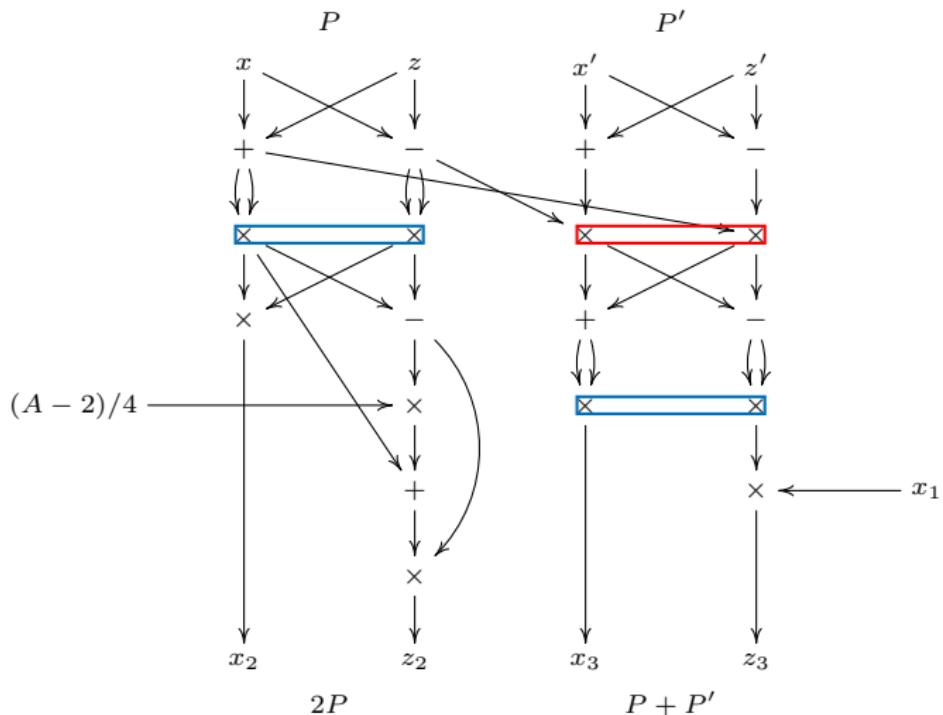
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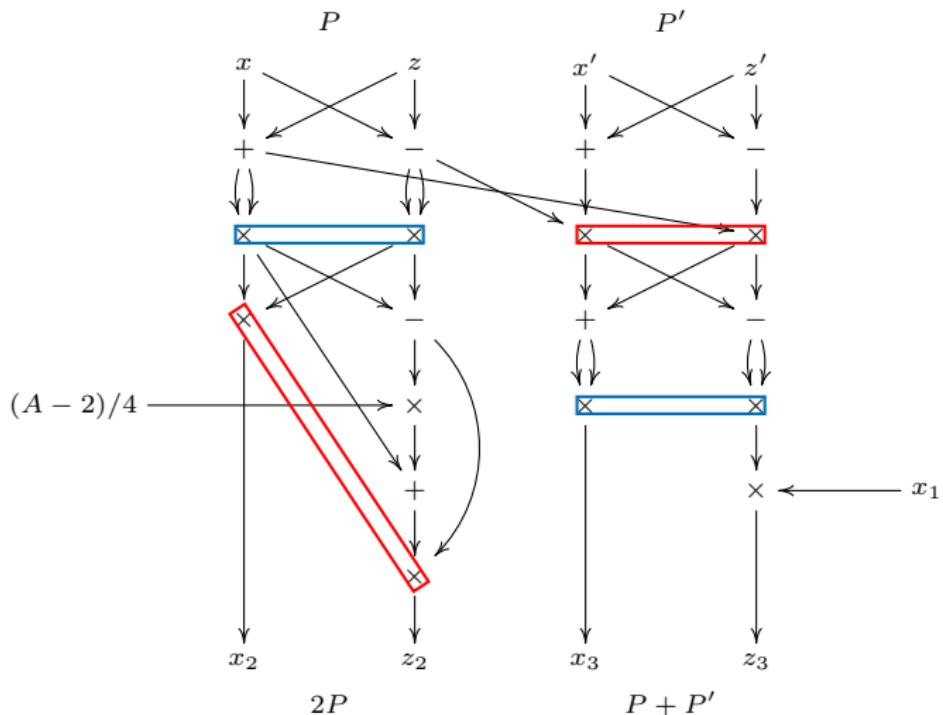
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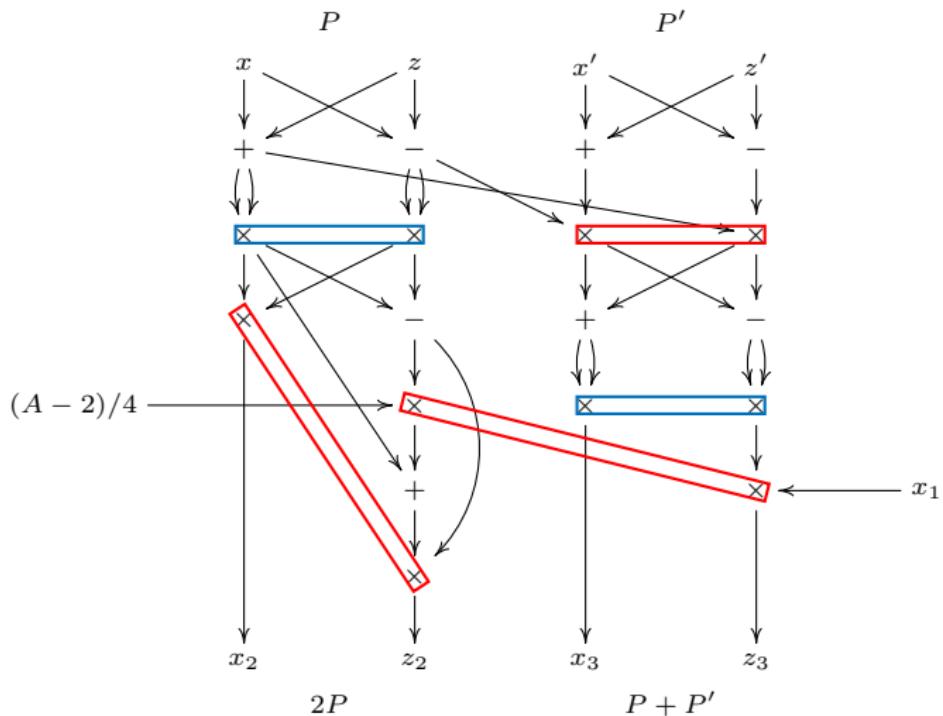
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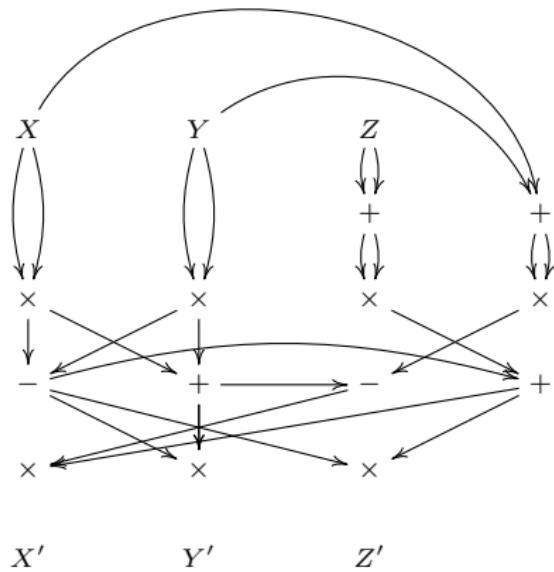
Exploiting parallelism: ladder step



www.hyperelliptic.org/EFD/g1p/auto-montgom-xz.html#ladder-mladd-1987-m

Exploiting parallelism: doubling (twisted Edwards curves)

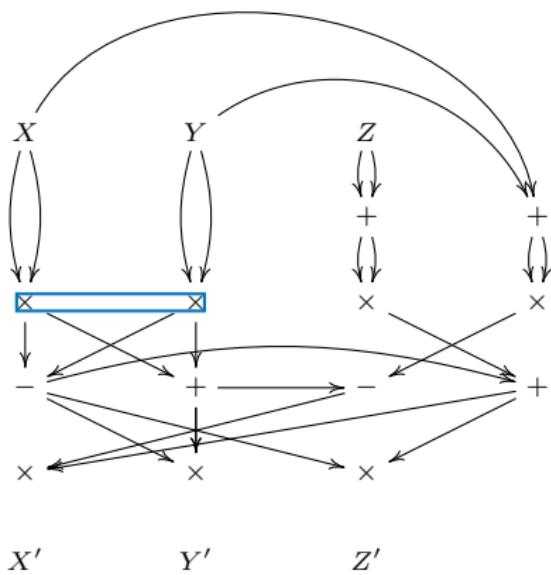
- Let $(X : Y : Z) := (X/Z, Y/Z)$
- Goal: compute $(X' : Y' : Z') = 2(X : Y : Z)$



www.hyperelliptic.org/EFD/g1p/auto-twisted-extended-1.html#doubling-dbl-2008-hwcd

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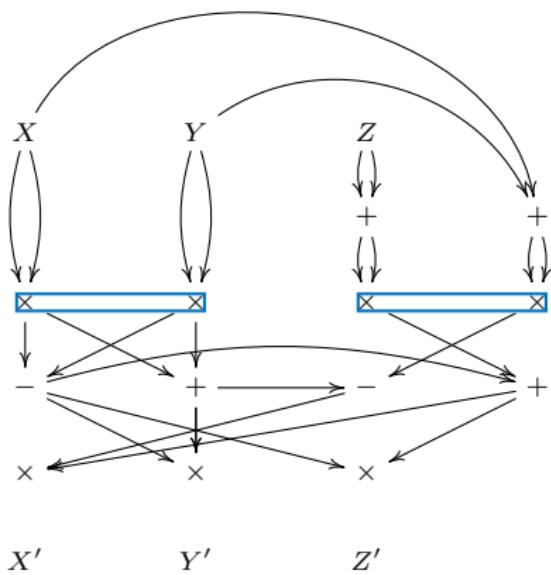
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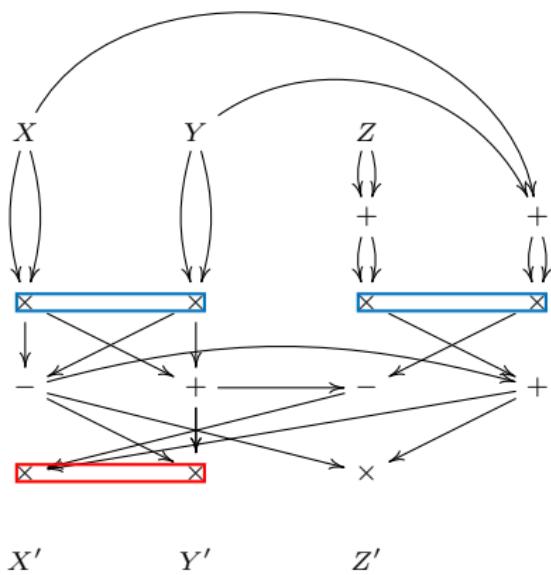
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Exploiting parallelism: doubling (twisted Edwards curves)

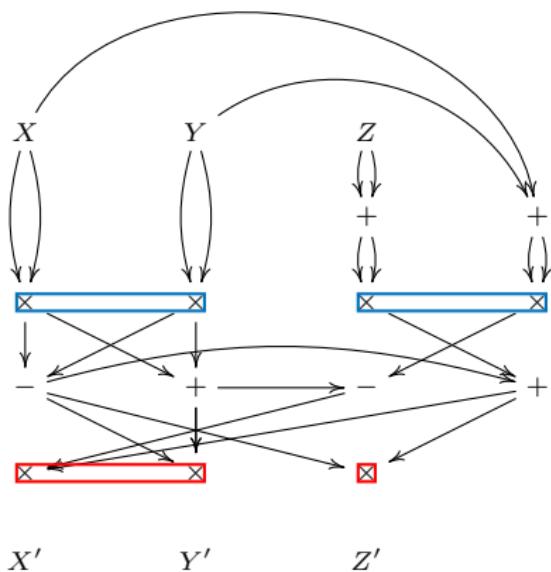
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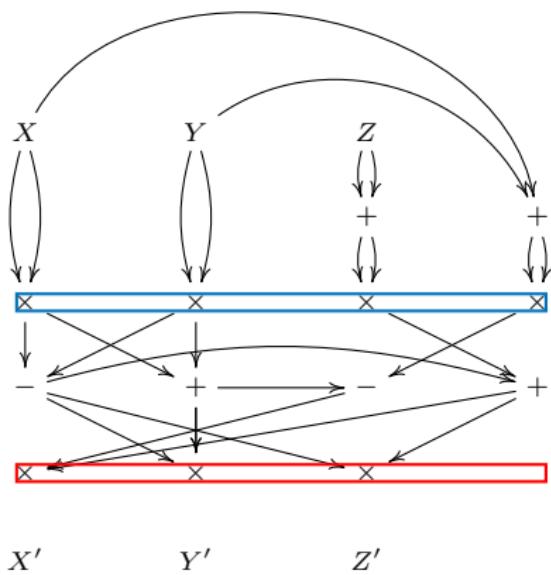
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Field representation: case of $\mathbb{F}_{2^{255}-19}$

- Intuition: radix-2⁶⁴ representation
 - each field elements in represented by 4 **limbs**

$$f = f_0 + f_1 2^{64} + f_2 2^{128} + f_3 2^{192}$$

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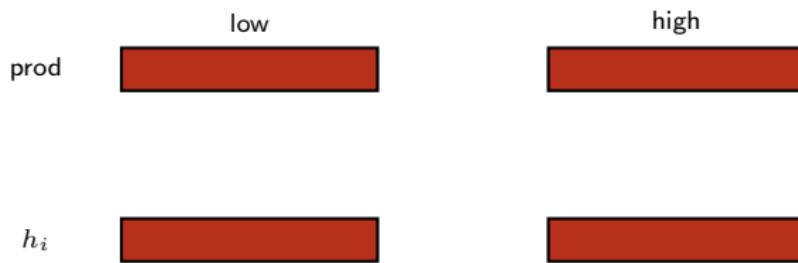
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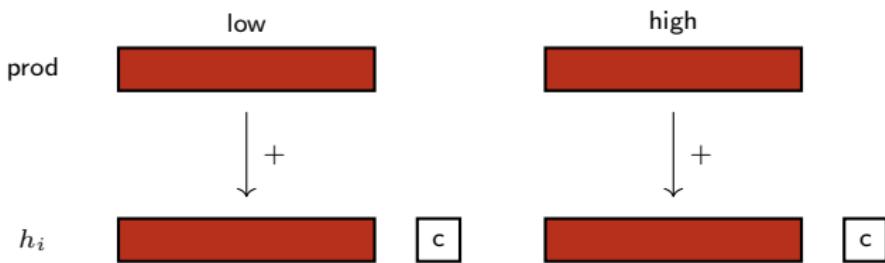
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- Making use MULX: “64 × 64 → 64 64”
- Lots of carries!

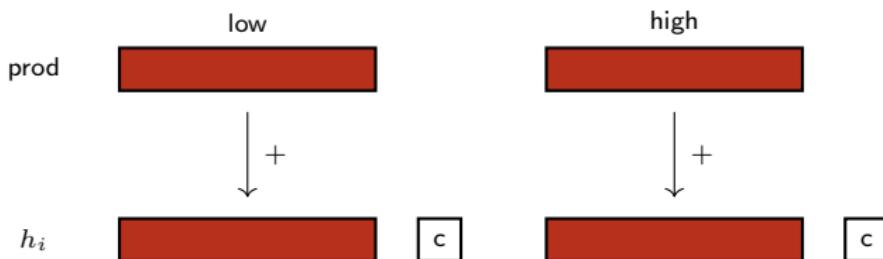
Adding products of the limbs



Adding products of the limbs



Adding products of the limbs



- adding 128-bit products produces 2 carry bits:
→ require 2 “addtion with carry” (adc) instructions
- adc can be expensive:
6x slower than add in terms of throughput on some Intel CPUs

Redundant representation

- Radix-51 representation

$$f = f_0 + f_1 2^{51} + f_2 2^{102} + f_3 2^{153} + f_4 2^{204}$$

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- Adding upper 64 bits does not generate carries!
⇒ reducing (roughly) half of the adc's

Reduction (carries)

- Carry $h_i \rightarrow h_{i+1}$ (consider radix 2^b):

$$c = h_i \gg b, \quad h_{i+1} = h_{i+1} + c, \quad h_i = h_i - c$$

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(Drawback: suffering from long latency)

- Reducing latency by interleaving carries:

$$h_0 \rightarrow h_1 \rightarrow h_2 \rightarrow h_3 \rightarrow h_4 \rightarrow h_5 \rightarrow h_6$$

$$h_5 \rightarrow h_6 \rightarrow h_7 \rightarrow h_8 \rightarrow h_9 \rightarrow h_0 \rightarrow h_1$$

Instruction-level optimization

instructions	ports	latency	reciprocal throughput
PADD/SUB(S,US)B/W/D/Q	p15	1	0.5
PMULDQ	p0	5	1
PSLLDQ, PSRLDQ	p5	1	1
PAND PANDN POR PXOR	p015	1	0.33

www.agner.org/optimize/instruction_tables.pdf

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www.agner.org/optimize/instruction_tables.pdf

- Each execution ports can handle 1 (micro-) instruction per cycle
- Useful for estimating the actual performance
 - PADD or PSLLDQ to multiply by 2?
- More on www.agner.org

Field inversion

- Used for converting from $(X : Y : Z)$ to $(X/Z, Y/Z)$, for example
 - typically only once

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 - $a, b \mapsto x, y$ s.t. $xa + yb = \gcd(a, b)$
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Elliptic curves

Conductor

How do you compute the conductor of an elliptic curve (over \mathbb{Q}) in Sage?

Once you define an elliptic curve E in Sage, using the `EllipticCurve` command, the conductor is one of several "methods" associated to E . Here is an example of the syntax (borrowed from section 2.4 "Modular forms" in the tutorial):

```
sage: E = EllipticCurve([1,2,3,4,5])
sage: E
Elliptic Curve defined by  $y^2 + x*y + 3*y = x^3 + 2*x^2 + 4*x + 5$  over Rational Field
sage: E.conductor()
10351
```

j -invariant

How do you compute the j -invariant of an elliptic curve in Sage?

Other methods associated to the `EllipticCurve` class are `j_invariant`, `discriminant`, and `weierstrass_model`. Here is an example of their syntax.

```
sage: E = EllipticCurve([0, -1, 1, -10, -20])
sage: E
Elliptic Curve defined by  $y^2 + y = x^3 - x^2 - 10*x - 20$  over Rational Field
sage: E.j_invariant()
-122023936/161051
sage: E.short_weierstrass_model()
Elliptic Curve defined by  $y^2 = x^3 - 13392*x - 1080432$  over Rational Field
sage: E.discriminant()
-161051
sage: E = EllipticCurve(GF(5),[0, -1, 1, -10, -20])
sage: E.short_weierstrass_model()
Elliptic Curve defined by  $y^2 = x^3 + 3*x + 3$  over Finite Field of size 5
sage: E.j_invariant()
4
```